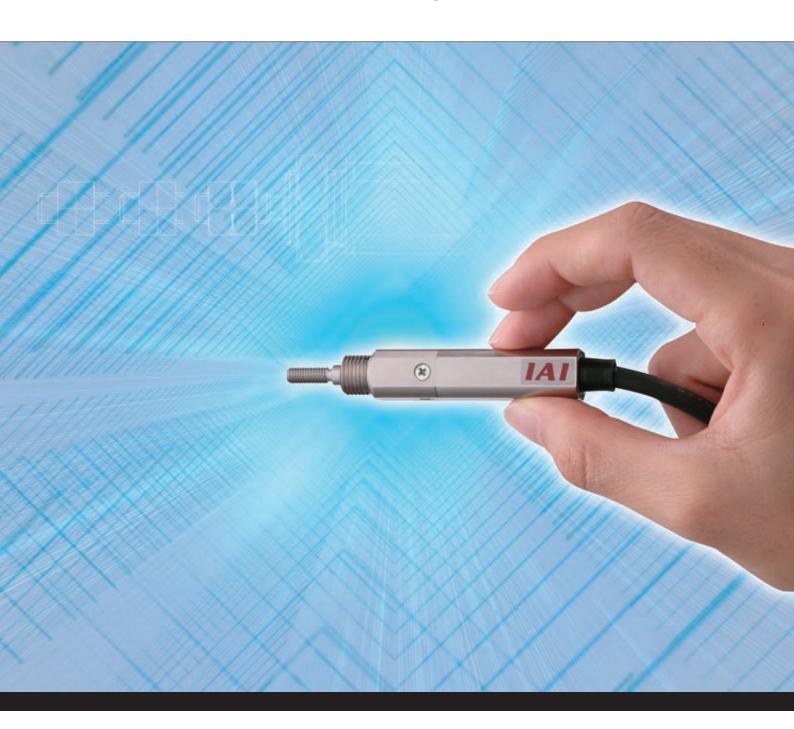




Micro Cylinder RCD



www.iai-automation.com

New Ultra-Compact Motorized Cylinder with 12mm Cross-Section

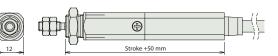


Features

Ultra-compact size enables it to replace compact air cylinders

Ultra-compact size has been achieved, with a cross-section of only 12 mm with a body length as short as 60 mm.

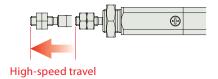
The Micro Cylinder RCD is small enough to replace compact air cylinders used for short-stroke travel, pressing, hoisting, etc.



Slim actuator

High-speed performance with maximum acceleration/deceleration of 1 G and maximum speed of 300 mm/s

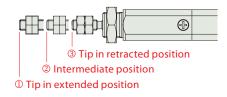
The Micro Cylinder RCD incorporates a newly developed brushless DC motor that generates sufficient torque despite its compact size. Its high-speed performance with maximum accelleration/deceleration of 1 G and maximum speed of 300 mm/s is highly effective in reducing cycle time in a variety of systems.



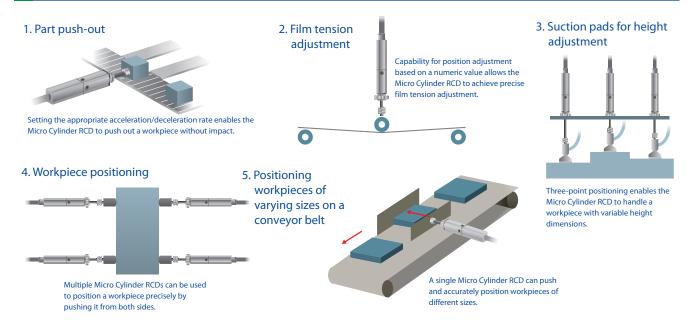
Capable of 3-/512-point positioning, acceleration rate adjustment, and pressing

The Micro Cylinder RCD easily achieves 3-point (by DSEP) or 512point (by DCON-CA) positioning and acceleration/deceleration rate adjustments, which are difficult to achieve using air cylinders.

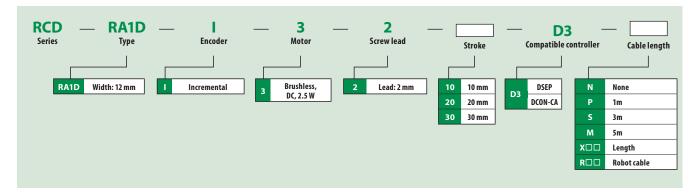
Push-motion operation similar to that available with air cylinders is also possible, and the force exerted during a push-motion operation is adjustable.



Application Examples



Actuator Model Description



Actuator Specifications

ltem		Description
Drive method	-	Lead screw with 3mm diameter and 2mm lead
Stroke	(mm)	10/20/30
Rated acceleration	(G)	1.0
Rated speed (Note 1)	(mm/s)	300
Rated thrust	(N)	4.2
Payload (Note 2)	(kg)	Horizontal 0.7, Vertical 0.3
Positioning repeatability (Notes 3, 4)	(mm)	±0.05
Encoder resolution	(pulses/rev)	400
Lost motion (Notes 3, 4)	(mm)	0.2 or smaller
Rod static allowable load moment	(Nm)	0.02
Rod non-rotating accuracy	(degrees)	±3
Service life	(cycles)	10 million cycles (for horizontal and vertical)
Ambient operating temperature; Humidity	-	0-40°C; 10%-85% RH or less

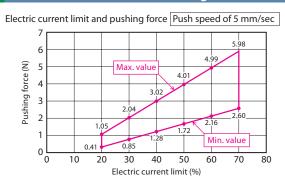
Note 1: The rated speed may not be achieved, depending on the stroke.

Note 2: When using an extremal guide and a free joint.

Note 3: Value shown is the initial value, which may change depending on usage conditions because a lead screw is used.

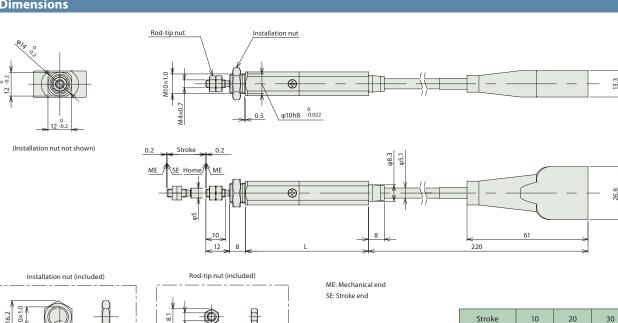
Note 4: fp ossitioning repeatability is required, take lost motion into account and perform positioning from only one direction.

Electric Current Limit and Pushing Force



Note: The ranges shown in this graph take into account efficiency deterioration caused by wear on the lead screw. Always use the product within the maximum and minimum values

Dimensions





IAI America Inc.

USA Headquarters 2690 W 237t h Str., Torrance, CA 90505, USA Tel.: +1-310-891-6015 Fax: +1-310-891-0815

IAI Industrieroboter GmbH

Europe Headquarters Ober der Röth 4, D-65824 Schwalbach, Germany Tel.: +49-6196-8895-0 Fax: +49-6196-8895-24

IAI CORPORATION

Japan Headquarters 645-1 Shimizu Hirose, Shizuoka 424-0102, Japan Tel.: +81-543-64-5105 Fax: +81-543-64-5182

52

47

Weight (g)

62

51

72

55